

RC Filter Circuits

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Constants and Definitions:

$$k \equiv 1000 \cdot \text{ohm} \quad \text{kHz} := 1000 \cdot \text{Hz} \quad \text{MHz} := 10^6 \cdot \text{Hz} \quad \mu\text{F} := 10^{-6} \cdot \text{farad} \quad \text{dB}(x) := 20 \cdot \log(x)$$

$$V_{\text{in}} := 1 \cdot \text{volt} \quad R \equiv 5 \cdot k \quad C \equiv 1 \cdot \mu\text{F}$$

Frequency Range for graphing filter response:

$$\text{Low Frequency Limit} \quad f_{\text{low}} := 0.01 \cdot \text{Hz}$$

$$\text{High Frequency Limit} \quad f_{\text{high}} := 10 \cdot \text{MHz}$$

Frequency Index

$$f := \log(f_{\text{low}} \cdot \text{Hz}^{-1}), \log(f_{\text{low}} \cdot \text{Hz}^{-1}) + \left[\frac{\log\left(\frac{f_{\text{high}}}{f_{\text{low}}}\right)}{500} \right] \dots \log(f_{\text{high}} \cdot \text{Hz}^{-1})$$

$$g(f) := 10^f \cdot \text{Hz}$$

Equations for RC Filters:

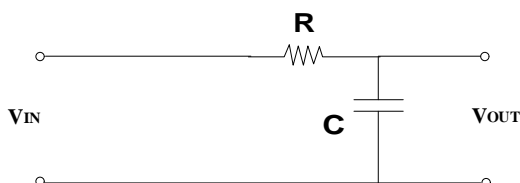
$$A_{\text{HP}}(f) := \frac{(2 \cdot \pi \cdot g(f)) \cdot R \cdot C}{\sqrt{(2 \cdot \pi \cdot g(f))^2 \cdot R^2 \cdot C^2 + 1}} \quad \text{Amplitude of high pass filter}$$

$$A_{\text{LP}}(f) := \frac{1}{\sqrt{(2 \cdot \pi \cdot g(f))^2 \cdot R^2 \cdot C^2 + 1}} \quad \text{Amplitude of low pass filter}$$

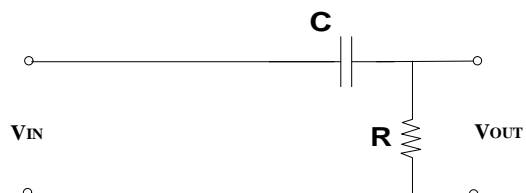
$$\phi_{\text{HP}}(f) := \text{atan}\left[\frac{1}{(2 \cdot \pi \cdot g(f)) \cdot R \cdot C}\right] \quad \text{Phase of high pass filter}$$

$$\phi_{\text{LP}}(f) := \left[-\text{atan}\left[\frac{-1}{(2 \cdot \pi \cdot g(f)) \cdot R \cdot C}\right] - \frac{\pi}{2} \right] \quad \text{Phase of low pass filter}$$

Low Pass Filter



High Pass Filter



$$R \cdot C = 0.005 \cdot \text{sec}$$

$$\frac{1}{2 \cdot \pi \cdot R \cdot C} = 31.831 \cdot \text{sec}^{-1}$$

